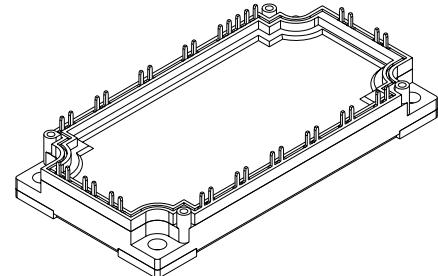
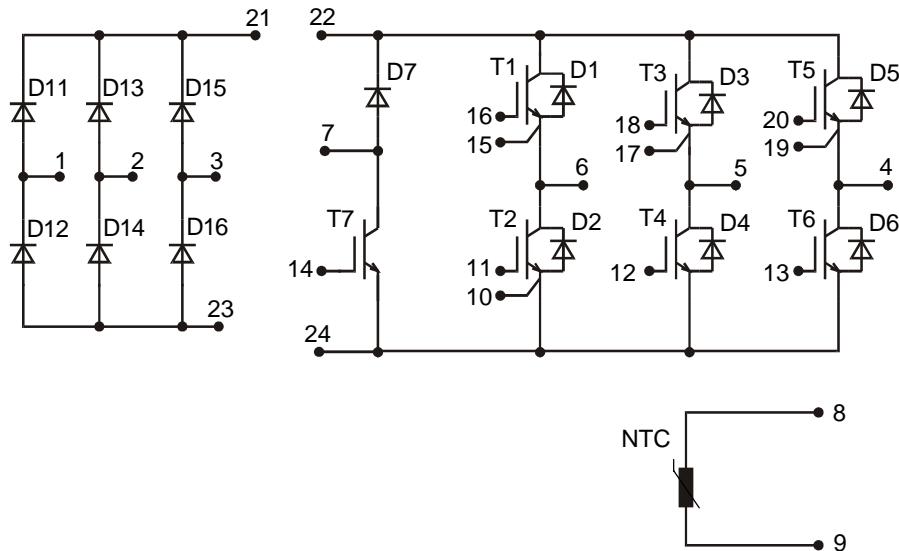


## Converter - Brake - Inverter Module (CBI3)



Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600V$	$V_{CES} = 1200 V$	$V_{CES} = 1200 V$
$I_{FAVM} = 70 A$	$I_{C25} = 52 A$	$I_{C25} = 90 A$
$I_{FSM} = 700 A$	$V_{CE(sat)} = 2.2 V$	$V_{CE(sat)} = 1.9 V$

### Input Rectifier Bridge D11 - D16

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$		1600		V
$I_{FAV}$	$T_c = 80^\circ\text{C}$ ; sine $180^\circ$	50		A
$I_{DAVM}$	$T_c = 80^\circ\text{C}$ ; rectangular; $d = \frac{1}{3}$ ; bridge	140		A
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}$ ; $t = 10$ ms; sine 50 Hz	700		A
$P_{tot}$	$T_c = 25^\circ\text{C}$	135		W

### Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

### Features

- High level of integration - only one power semiconductor module required for the whole drive
- IGBT technology with low saturation voltage, low switching losses and tail current, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Symbol	Conditions	Characteristic Values		
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)	min.	typ.
$V_F$	$I_F = 50 A$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.1	1.3
			1.1	V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.8	0.05 mA
				mA
$R_{thJC}$	(per diode)			0.94 K/W

**Output Inverter T1 - T6**

<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200		V
$V_{GES}$	Continuous	$\pm 20$		V
$I_{C25}$	$T_C = 25^\circ\text{C}$	90		A
$I_{C80}$	$T_C = 80^\circ\text{C}$	62		A
$I_{CM}$	$V_{GE} = \pm 15 \text{ V}$ ; $R_G = 22 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$	100		A
$V_{CEK}$	RBSOA; Clamped inductive load; $L = 100 \mu\text{H}$	$V_{CES}$		
$t_{sc}$ <b>(SCSOA)</b>	$V_{CE} = 900 \text{ V}$ ; $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 22 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	10	$\mu\text{s}$	
$P_{tot}$	$T_C = 25^\circ\text{C}$	350		W

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		$(T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		<b>min.</b>	<b>typ.</b>	<b>max.</b>

$V_{CE(\text{sat})}$	$I_C = 50 \text{ A}$ ; $V_{GE} = 15 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.9 2.1	2.4	V
$V_{GE(\text{th})}$	$I_C = 2 \text{ mA}$ ; $V_{GE} = V_{CE}$	4.5	6.5	V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.8	0.8	mA
$I_{GES}$	$V_{CE} = 0 \text{ V}$ ; $V_{GE} = \pm 20 \text{ V}$		200	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	$\left. \begin{array}{l} \text{Inductive load, } T_{VJ} = 125^\circ\text{C} \\ V_{CE} = 600 \text{ V}; I_C = 50 \text{ A} \\ V_{GE} = \pm 15 \text{ V}; R_G = 22 \Omega \end{array} \right\}$	150 60 680 50 6 5		ns ns ns ns mJ mJ
$C_{ies}$ $Q_{Gon}$	$V_{CE} = 25 \text{ V}$ ; $V_{GE} = 0 \text{ V}$ ; $f = 1 \text{ MHz}$ $V_{CE} = 600 \text{ V}$ ; $V_{GE} = 15 \text{ V}$ ; $I_C = 50 \text{ A}$	3.8 500		nF nC
$R_{thJC}$	(per IGBT)		0.35	K/W

**Output Inverter D1 - D6**

<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>		
$I_{F25}$	$T_C = 25^\circ\text{C}$	110		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	70		A

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		<b>min.</b>	<b>typ.</b>	<b>max.</b>
$V_F$	$I_F = 50 \text{ A}$ ; $V_{GE} = 0 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	2.1 1.5	2.5	V
$I_{RM}$ $t_{rr}$	$\left. \begin{array}{l} I_F = 60 \text{ A}; di_F/dt = -500 \text{ A}/\mu\text{s} \\ V_R = 600 \text{ V}; V_{GE} = 0 \text{ V} \end{array} \right\}$	41 200		A ns
$R_{thJC}$	(per diode)		0.61	K/W

**Brake Chopper T7**

<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>		
$V_{CES}$	$T_{VJ} = 25^\circ C$ to $150^\circ C$	1200		V
$V_{GES}$	Continuous	$\pm 20$		V
$I_{C25}$	$T_C = 25^\circ C$	52		A
$I_{C80}$	$T_C = 80^\circ C$	35		A
$I_{CM}$	$V_{GE} = \pm 15 V$ ; $R_G = 39 \Omega$ ; $T_{VJ} = 125^\circ C$	50		A
$V_{CEK}$	RBSOA; Clamped inductive load; $L = 100 \mu H$	$V_{CES}$		
$t_{sc}$ <b>(SCSOA)</b>	$V_{CE} = 900 V$ ; $V_{GE} = \pm 15 V$ ; $R_G = 39 \Omega$ ; $T_{VJ} = 125^\circ C$ non-repetitive	10		$\mu s$
$P_{tot}$	$T_C = 25^\circ C$	225		W

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		( $T_{VJ} = 25^\circ C$ , unless otherwise specified)		
		<b>min.</b>	<b>typ.</b>	<b>max.</b>
$V_{CE(sat)}$	$I_C = 35 A$ ; $V_{GE} = 15 V$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$	2.2 2.5	2.8 V	V
$V_{GE(th)}$	$I_C = 1 mA$ ; $V_{GE} = V_{CE}$	4.5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0 V$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		0.1 0.1	mA mA
$I_{GES}$	$V_{CE} = 0 V$ ; $V_{GE} = \pm 20 V$		200	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ C$ $V_{CE} = 600 V$ ; $I_C = 35 A$ $V_{GE} = \pm 15 V$ ; $R_G = 39 \Omega$	150 60 680 50 4.2 3.5		ns ns ns ns mJ mJ
$C_{ies}$ $Q_{Gon}$		2 250		nF nC
$R_{thJC}$			0.55	K/W

**Brake Chopper D7**

<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>		
$V_{RRM}$	$T_{VJ} = 25^\circ C$ to $150^\circ C$	1200		V
$I_{F25}$	$T_C = 25^\circ C$	25		A
$I_{F80}$	$T_C = 80^\circ C$	16		A
<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>		
		<b>min.</b>	<b>typ.</b>	<b>max.</b>
$V_F$	$I_F = 35 A$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$	3.0 2.3	3.4 V	V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		0.1	mA mA
$I_{RM}$ $t_{rr}$	$I_F = 15 A$ ; $di_F/dt = -400 A/\mu s$ ; $T_{VJ} = 125^\circ C$ $V_R = 600 V$	16 130		A ns
$R_{thJC}$			2.1	K/W

## Temperature Sensor NTC

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$ $B_{25/50}$	$T = 25^\circ\text{C}$	4.75	5.0 3375	5.25 k $\Omega$ K

## Module

Symbol	Conditions	Maximum Ratings		
$T_{VJ}$		-40...+150	$^\circ\text{C}$	
$T_{JM}$		150	$^\circ\text{C}$	
$T_{stg}$		-40...+125	$^\circ\text{C}$	
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~	
$M_d$	Mounting torque (M5)	3 - 6	Nm	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m $\Omega$
$d_s$	Creepage distance on surface	6		mm
$d_A$	Strike distance in air	6		mm
$R_{thCH}$	with heatsink compound	0.01		K/W
Weight		300		g

Dimensions in mm (1 mm = 0.0394")

